

Name of organization MARIN	Year of information updating 2017															
Year established 1932	Year of joining the ITTC 1932															
Address Haagsteeg 2 6708 PM Wageningen The Netherlands	Status in the ITTC Advisory Council member															
Contact details (phone, fax, e-mail) +31 317 493 911 +31 317 493 235 info@marin.nl	Website www.marin.nl															
Type of facility Towing tank / Seakeeping basin / Cavitation tunnel	Year constructed/upgraded 1973 / 2000 / 2011															
Name of facility Depressurised Wave Basin (DWB)	Location (if different from the above address) Marconistraat 20 6716 AK Ede The Netherlands															
Main characteristics (dimensions of tank/basin/test section; for simulators: full mission, part task or desk top) Length 220 m Width 16 m Water depth 8 m																
Drawings of facility																
<table border="0"> <tr> <td>1 Harbour</td> <td>4 Air lock</td> <td>7 Measuring frame</td> <td>10 Short side wave damper</td> <td>13 Short side wave generator</td> </tr> <tr> <td>2 Lift opening</td> <td>5 Observation module</td> <td>8 Main carriage</td> <td>11 Long side wave damper</td> <td>14 Silent and Offshore carriage</td> </tr> <tr> <td>3 Control room</td> <td>6 Sub carriage</td> <td>9 Pressure cabin</td> <td>12 Long side wave generator</td> <td>15 Hydrophone array</td> </tr> </table>		1 Harbour	4 Air lock	7 Measuring frame	10 Short side wave damper	13 Short side wave generator	2 Lift opening	5 Observation module	8 Main carriage	11 Long side wave damper	14 Silent and Offshore carriage	3 Control room	6 Sub carriage	9 Pressure cabin	12 Long side wave generator	15 Hydrophone array
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Detailed characteristics (carriages, wave/current/wind generators, instrumentations, etc.)																
Description of carriage																
Main carriage	<p>Unmanned, motor driven, four drive wheels</p> <p>Subcarriage which can travel through air lock to harbour outside depressurised basin</p> <p>Observation module with traversing frames to position camera's and lights around the stern of a model for cavitation observations</p>															
Type of drive system and total power	Servo controlled, 4 * 110 kW															
Maximum carriage speed	6 m/s															
Other capabilities	<p>Test sections which can be exchanged in the sub-carriage:</p> <ul style="list-style-type: none"> - test frame - seakeeping - hexapod - VIM for TLP's - Cavitation observation module 															
Silent running carriage	<p>Unmanned, motor driven, four drive wheels</p> <p>Lightweight, low noise level for propeller radiated noise measurements</p> <p>Rotating ring below carriage for fitting mooring lines for testing offshore structures (semisubmersible, spar, wave energy converters)</p>															

Type of drive system and total power	Servo controlled, 4 * 15 kW
Maximum carriage speed	6 m/s
Wave generator capability	Short side <ul style="list-style-type: none"> - Regular waves 1.10 m at a peak period of 2.5 s - Irregular wave 0.70 m at a peak period of 2.5 s Long side <ul style="list-style-type: none"> - Regular waves 0.80 m at a peak period of 2.5 s - Irregular wave 0.40 m at a peak period of 2.5 s Wave direction 0 – 360 deg. Fitted with anti reflecting compensation (ARC)
Wave maker type:	Dry back, flap type wave generator <ul style="list-style-type: none"> - Short side 24 flaps of 0.6 m wide, hinge depth 2.5 m - Long side 200 flaps of 0.5 m wide, hinge depth 1.8 m
Beach type and length	Short side: <ul style="list-style-type: none"> - Circular beach, length 12 m, fixed with moveable section on centre line Long side: <ul style="list-style-type: none"> - circular beach, length 5 m, moveable, lowered in case of 0 or 180 deg wave direction
Other capabilities	According to the laws of similarity which apply for cavitation the ambient air pressure in the basin must be reduced to the inverse of model scale. Depressurised conditions, minimum pressure 35 mbar(a) De-aeration of basin water by means of bubble injection
Vacuum pumps	3 vacuum pumps: 12,000 m ³ /h, 25 mbar(a)
Hexapod	Stroke x,y,z = 600, 600 and 400 mm
Instrumentation	Dynamometers for: <ul style="list-style-type: none"> - thrust and torque in propeller hub, - 6 component force balances, - thrusters Photo, video, underwater video, High speed cavitation observation cameras (10 kfps), stroboscopes, Lighting for high speed camera observation Wave height transducers Pressure transducers for pressure fluctuations Hydrophones inside ship model Hydrophone array in basin Air content of basin water
Model size range	0.3 - 12 m
Model tracking techniques	NDI camera (optical tracking)
Test performed	
Still water performance	Resistance and propulsion test in calm water Cavitation inception and observations in calm water Pressure fluctuations measurements Radiated propeller noise measurements Flow noise measurements
Seakeeping	

